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	Hall	Ticket Number :												_		
	Code	e: 19A353T		,									_		R-19	
		III B.Tech. I Se	mes	ster	Sup	pler	nen	tary	Exc	ımin	atio	ns N	100/[	De	c 2022	
					_				e Ele			-I				
		x. Marks: 70 ver any five full qu	vestic				ng oi	ne q	ginee uesti			each	unit (		Time: 3 Hours 14 = 70 Marks)	
								*****								
1.	۵)	What are the	m	anıı	fact	urin		IIT–		atio	ne 1	n h	A CC	าทร	sidered by	
١.	a)	design?													-	7M
	b)	An unknown to the lower of the maxim what is the countries the countries to the transfer of th	end um orres	of a ins	vei tant ndin	tica ane	l ba ous	r 3 ext	m lo tens	ng ion	and is l	60 kno	0 mn wn t	n <sup>2</sup> o l	in section. be 2 mm,	7M
		Take L = 200	KIN/	/ 1 1 11 1	١.			OR								/ IVI
2.	a)	Enumerate a and state at	-					imo	nly			_		_		
		each.														7M
	b)	Find out the r	num	bers	s of	R10	) ba	sic s	serie	es fr	om	1 to	10.			7M
							UN	IT-	I							
3.	a)	Define endurendurance lin						uss	the	e fa	acto	rs v	whicl	h	affect the	7M
	b)	Determine the cyclic fluctual. The endurant Take factor of concentration.	tion ce I of sa	fro limit afety	m 1 is / = '	50 360 1.5;	kN Mf	(ter Pa a	nsio and	n) to	o 29 ld s	5 kl tren	V (co	om is	pression). 400 MPa.	7M
								OR								
4.	a)	Describe Sod of machine m		_								-	tion 1	for	designing	7M
	b)	Determine the with a fatigue a tensile yield varying axial has a stress of	stre d str load	engt reng d fro	th (c gth ( om \	com of 3 N <sub>min</sub>	plet 50M =-	e st 1Pa. 300	ress Th × 1	rev e m 0 <sup>3</sup> N	ers eml to	al), ber W <sub>m</sub>	e =: is su <sub>ax</sub> =70	26: ubj 00:	5MPa and ected to a ×10³N and	7M
		าเนง ผ งแ เรงง (			ian		UN			USC	, ial	JUI	01 30	AI C	ty 40 2.0.	<i>i</i> 1VI
5.	a۱	List out the ac	dvar	ntac	ies a	l				ges	of s	scre	w ini	ints	S.	7M
٥.	u)			49	, 55 (		J			<b>ჟ</b> 55	٥. ٥	. J. J	اکر		<del>-</del> -	/ IVI

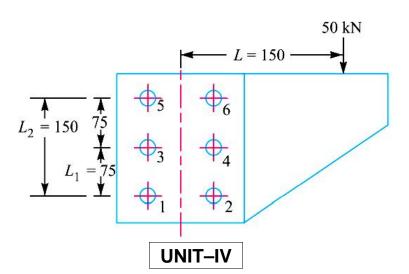
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b) An electric motor weighing 10 kN is lifted by means of an eye bolt. The eye bolt is screwed into the frame of the motor. The eye bolt has coarse threads. It is made of plain carbon steel 30C8 (S<sub>yt</sub>=400 N/mm<sup>2</sup>) and the factor of safety is 6. Determine the size of the bolt.

7M

OR

6. a) A bracket is bolted to a column by 6 bolts of equal size as shown in Fig. It carries a load of 50 kN at a distance of 150 mm from the centre of column. If the maximum stress in the bolts is to be limited to 150MPa, determine the diameter of bolt.



14M

7. a) Design a sleeve and cotter joint to resist a tensile load of 60 kN. All parts of the joint are made of the same material with the following allowable stresses:  $_{\rm t}$  = 60 MPa; = 70 MPa; and  $_{\rm c}$  = 125 MPa

14M

OR

8. a) What are the applications of knuckle joint?

4M

b) Design a knuckle joint to transmit 140 kN, with permissible stresses in tension; shear and compression are 75 Mpa; 60 Mpa and 150 Mpa respectively.

10M

UNIT-V

9. a) How the shaft is designed when it is subjected to twisting moment and bending moment?

6M

b) A shaft is transmitting 100 kW at 180 r.p.m. If the allowable shear stress in the material is 60 MPa, find the suitable diameter for the shaft. The shaft is not to twist more than 1° in a length of 3 m. Take C = 80 GPa.

**8M** 

OR

10. a) Classify the shaft coupling.

6M

b) Design of a muff coupling which is used to connect two steel shafts transmitting 40 kW at 350 r.p.m. The material for the shafts and key is plain carbon steel for which allowable shear and crushing stresses may be taken as 40 MPa and 80 MPa respectively. The material for the muff is cast iron for which the allowable shear stress may be assumed as 15 MPa.

8M

# ANNAMACHARYA INSTITUTE OF TECHNOLOGY & SCIENCES, RAJAMPET (AUTONOMOUS)

III B.Tech I Semester <u>ME</u> Supplementary Examination 19AC53T-Universal Human Values-II

Date:-26-1	2-2022			 	 	 Duration: 3Hrs.
<b>Answer all</b>	of the fo	allowing	7			5X10=50 Marks

		Marks	Course Outcomes	Bloom's Level
1	Distinguish between Animal consciousness and Human	10M	1	2
	Consciousness.			
	$(\mathbf{OR})$			
2	What is the qualitative difference between the activities of the Self and those of the Body? Illustrate with few examples.	10M	2	2
3	What are the basic Human aspirations and what are the	10M	2	2
	requirements to fulfil them? Indicate their correct priority with examples.			
	(OR)			
4	Why is right understanding required in relationship for mutual	10M	5	2
	happiness? Illustrate with the help of two examples from your life.			
5	How is behaviour and work decided? Is it decided by the Body or	10M	3	2
	by the Self?			
	$(\mathbf{OR})$			
6	What is imagination? Is it taking place continuously or is it a temporary activity that you can start and stop at will? Justify your	10M	5	2
	answer with some examples.			
7	How is trust the foundational value of relationship?	10M	4	3
	(OR)			
8	How is behaviour and work decided? Is it decided by the Body or	10M	3	2
	by the Self?			
9	Distinguish between units and space.	10M	5	2
	(OR)			
10	What do you mean by definitiveness in Ethical Human conduct? Support your answer with an example.	10M	2	2

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III B.Tech. I Semester Supplementary Examinations Nov/Dec 2022

## **Industrial Management**

(Mechanical Engineering)

Max. Marks: 70 Time: 3 Hours Answer any five full questions by choosing one question from each unit (5x14 = 70 Marks)

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			Marks	CO	BL
		UNIT-I			
1.	a)	Explain the concept, and applications of committee organization	7M	CO1	L1
	b)	Describe the functional organization and applications of functional organization	7M	CO1	L1
		OR			
2.	a)	Explain the concept, advantages, disadvantages and applications of line and			
۷.	aj	staff organization	7M	CO1	L1
	b)	Describe matrix organization.	7M	CO1	L1
		UNIT-II			
3.		Define plant layout. Explain the types of Plant layout in detail	14M	CO2	L1
		OR			
4.	a)	Discuss the factors affecting plant location	7M	CO2	L1
••	b)	Suggest suitable layout to establish a cement industry	7M	CO2	L2
	D)	UNIT-III	<i>1</i> IVI	002	LZ
5.	a)	Define time study and explain its objectives	7M	CO3	L1
	b)	Explain various steps involved in time study	7M	CO3	L2
	,	OR			
6.	a)	Describe the various methods involved for Performance rating in Work study.	7M	CO3	L1
	b)	Discuss the procedure of Method study	7M	CO3	L1
	,	UNIT-IV			
7.	a)	Explain the periodical review inventory control system	7M	CO4	L1
• •	b)	A manufacturer has to supply his customers 3600 units of its products per	, , , , ,	001	
	D)	year. Inventory carrying cost amounts Rs 1.2 per unit per annum. The set up			
		cost per run is Rs 80. Determine i)Economic order quantity ii)Number of orders			
		per year	7M	CO4	L1
		OR			
8.	a)	Describe the costs associated with the inventories	7M	CO4	L2
٠.	b)	A manufacturing company places a annual order of 48,000 units at a price of			
	υ,	Rs 20 per unit. Its carrying cost is 15% of unit price and the order cost is Rs			
		12 per order. Determine i)Economic order quantity ii)Number of orders per			
		year iii)Time between orders	7M	CO4	L2
		UNIT-V			
9.	a)	Describe job analysis	7M	CO5	L2
	b)	How do you determine the labour turnover rate?	7M	CO5	L2
	- /	OR			
10.	a)	Is personnel manager is Line or staff manager? support your answer with an			
	<i></i> /	example	7M	CO5	L2
	b)	Explain off the job training and on the job training methods	7M	CO5	L2
	,	***END***			

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III B.Tech. I Semester Supplementary Examinations Nov/Dec 2022

#### **Industrial Robotics**

(Mechanical Engineering)

Answer any five full questions by choosing one question from each unit (5x14 = 70 Marks)

**Blooms** Marks CO Level UNIT-I 1. Define Robotics? Explain robot configuration systems with neat sketches. 14M 1 2 OR 2. Define Robot? Write a short note on advantages and disadvantages of robots in human endeavor? 14M 1 2 UNIT-II Define forward and reverse kinematics of robot and differentiate between 3. forward and reverse kinematics of robots. 14M 2 2 OR 4. Derive Lagrangian robot equations for a two degree of freedom system? 14M 2 2 UNIT-III 2 5. Define path planning? Explain path planning with its block diagram. 14M 3 Explain briefly about the following terms: 6. (i) Skew motion 7M 3 2 2 7M 3 (ii) Joint integrated motion UNIT-IV

UNIT-V programming and offline programming

9. a) Distinguish between online programming and offline programming.
5 2
b) Explain briefly about industrial robot application.
7M 5
2

OR

Briefly explain the working principle of ANY TWO types of non-contact type

OR

Explain Pneumatic actuators system with neat sketch.

Explain the working of a stepper motor with neat sketch.

10. Explain briefly about the following terms:

sensors with a neat sketch.

Max. Marks: 70

7.

8. a)

b)

(i) Teach pendant robot programming 7M 5 2
(ii) Packaging and palletizing of products 7M 5 2

\*\*\*

14M

7M

7M

4

4

2

2

Time: 3 Hours

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#### **Machine Tools**

(Mechanical Engineering)

Max. Marks: 70 Time: 3 Hours

Answer any five full questions by choosing one question from each unit (5x14 = 70 Marks)

	Marks	СО	Blooms Level
UNIT-I			
1. a) With a neat sketch explain the geometry of a single point cutting tool?	10M	CO1	L1
b) Explain about ASA system in detail.	4M	CO1	L1
OR			
2. a) Why chip breakers are used? List various types of chip breakers and explain their significance.	7M	CO1	L3
b) Explain tool wear and flank wear with neat sketches?	7M	CO1	L2
		001	
UNIT-II			
3. Classify the lathe machines. Draw the Lathe machine with neat sketch and	4 4 5 4	000	1.4
show its parts?	14101	CO2	L4
OR	75.4	000	1.4
4. a) Describe any two work holding devices used in Lathe. With neat sketches?	/IVI	CO2	L1
<ul> <li>b) List out the various types of Dead centers in Lathe machine? Explain any two with neat sketches.</li> </ul>	7M	CO2	L1
UNIT-III			
5. Explain with a neat sketch the construction and working principle of a Radial			
Drilling machine.		CO3	L2
OR			
6. Show with neat sketch a Twist Drill and label the important elements.	14M	CO3	L2
UNIT-IV			
7. a) Explain different types of Grinding process in detail.	7M	CO4	L2
b) Write short notes on Abrasive types & usage	7M	CO4	L2
OR	7 101	004	
8. Clearly indicate the difference between Push and Pull type of Broaches.	14M	CO4	L1
		001	
UNIT-V			
9. What is the general function of Locators? List out the various types of			
Locators and explain any two with neat sketches	14M	CO5	L1
OR			
10. Define a Jig? List out the various types of Drill Jigs and explain any two with	4 4 1 4	005	
neat sketches  ***	14IVI	CO5	L2

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### **Rapid Prototyping**

(Mechanical Engineering)

Max. Marks: 70 Time: 3 Hours

Answer any five full questions by choosing one question from each unit (5x14 = 70 Marks)

		*****			
			Marks	СО	Blooms Level
1.	a) b)	UNIT-I  Compare rapid prototyping technology with CNC technology  With example explain the historical development of rapid prototyping	7M	1	2
	~,	technology	7M	1	3
		OR			
2.	a)	With example, explain the historical development of rapid prototyping technology	7M	1	2
	b)	List out the usage of RP parts in different fields	7M	1	3
		UNIT-II			
3.		Compare LOM with FDM with suitable reasons	14M	2	5
		OR			
4.	a)	Explain about pre-build, part build and post-build process of SLA	7M	2	2
	b)	How to perform post-processing in SLA technology	7M	2	5
		UNIT-III			
5.	a)	What are the different types of materials available for SLS system and give their applications.	7M	3	2
	b)	Differentiate indirect and direct SLS process	7M	3	2
		OR			
6.		Is it possible to use electron beam melting technology (EBM) technology to produce metal products, explain it?	14M	3	5
		UNIT-IV			
7.		List out different phases in reverse engineering (RE). Explain each phase.	14M	4	3
8.		OR  Define rapid tooling and classify it with suitable examples	14M	4	1
0.		Define Tapid tooling and classify it with suitable examples	14101	4	I
•		UNIT-V	4 4 8 4	_	0
9.		Differentiate rapid prototyping and rapid manufacturing	14M	5	2
10	c)	OR	71.1	E	2
10.	,	List the applications of RP technology in manufacturing	7M	5	3
	b)	Explain the applications of AM in various fields	7M	5	2

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#### **Automation & Robotics**

(Mechanical Engineering)

Max. Marks: 70 Time: 3 Hours Answer any five full questions by choosing one question from each unit (5x14 = 70 Marks)

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		*	*****		,	
		UNIT-		Marks	CO	BL
1.		Define automation. Describe the types of		14M	1	L2
		OR				
2.	a)	What is an Automated flow line? Discuss th	e objectives of flow line automation.	7M	1	L2
	b)	Explain the methods of work part transfer		7M	1	L2
		UNIT-I				
3.		Discuss about the elements of parts feed	ng devices.	14M	2	L2
		OR				
4.	a)	What is an Assembly process? Discus processes with suitable examples.	s the various types of assembly	7M	2	L2
	b)	What are the various types of assembly s	ystems? Explain them.	7M	2	L2
		UNIT-II	I			
5.	a)	Discuss the laws of Robotics		7M	3	L2
	b)	Write in brief the applications of Robots in	various fields.	7M	3	L2
		OR				
6.	a)	Explain the need of Robots in present cus	stomization	7M	3	L2
	b)	With neat diagrams explain about Robot j	oints	7M	3	L2
		UNIT-I	/			
7.	a)	With an example differentiate forward and	I inverse kinematics.	7M	4	L2
	b)	Write down about Jacobians differential to	ansformation	7M	4	L1
		OR				
8.		With a relevant schematic diagram desc	ribe the concept and relevance of			
		pitch, yaw and roll motions of a robot wris		14M	4	L4
		UNIT-\	1			
9.	a)	Compare Pneumatic, Hydraulic and elect	ric actuators	7M	5	L3
	b)	Describe the working of Encoders with ne	at diagrams.	7M	5	L2
		OR				
10.	a)	Explain about Touch and Tactile sensors.		7M	5	L2
	b)	Write about Robot Textual Languages		7M	5	L2

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## **Applied Thermodynamics-II**

(Mechanical Engineering)

Max. Marks: 70 Time: 3 Hours Answer any five full questions by choosing one question from each unit (5x14 = 70 Marks)

		deal-dealed			
			Marks	СО	Blooms Level
		UNIT-I			
1.		Discuss Reheat Rankine cycle with a neat sketch.	14M	CO1	L2
		OR			
2.		Explain the working construction of steam engines.	14M	CO1	L2
		UNIT-II			
3.	a)	Sketch Babcock and Wilcox boiler and explain its working.	10M	CO2	L2
	b)	Illustrate about fusible plug.	4M	CO2	L3
		OR			
4.		Derive an expression for natural draught and maximum discharge rate of			
		gases through the chimney for a given height of chimney, clearly stating the assumptions made.	14M	CO2	L6
		UNIT-III		002	20
5.	a)	Describe the function of nozzle & discuss various types of nozzles.	7M	CO3	L1
0.	b)	Discuss about super saturation flow of steam in nozzles.	7M	CO3	L2
	۵)	OR	7 101	000	
6.	a)	In a steam nozzle, steam expands from 4 bar to 1 bar. The initial velocity of steam is 60 m/s and the initial temperature is 200°C. Determine the exit velocity if the nozzle efficiency is 92%.	10M	CO3	L3
	b)	Define metastable state.	4M	CO3	L1
	٠,	UNIT-IV			
7.	a)	With the help of a neat sketch explain the working principle of Barometric jet			
	,	condenser.	8M	CO4	L2
	b)	Differentiate jet condensers with surface condensers.	6M	CO4	L4
		OR			
8.	a)	Steam enters a condenser at 36°C and with barometer reading 760 mm of			
,		Hg. If vacuum of 695 mm of Hg. is produced, find the vacuum efficiency?	8M	CO4	L3
	b)	Explain parallel flow jet condenser and explain its working principle.	6M	CO4	L2
		UNIT-V			
9.	a)	Explain velocity compounding in steam turbines with neat sketch	8M	CO5	L2
	b)	Compare impulse turbine with reaction turbine.	6M	CO5	L5
		OR			
10.		Steam leaves the nozzle of a single stage impulse turbine at 850 m/s. The nozzle angle is180 and the blade angles are 290 at the inlet and outlet. The friction coefficient is 0.9. Calculate blade velocity and steam mass flow rate			
		in kg/hr to develop 300 W power.	14M	CO5	L3
		***			