Hall <sup>-</sup>	Ticke	et Number :												F			1
Code	: 5G	272		J											R-1	5	
	١v	B.Tech. IS	Sem	este	er Re	egu	lar E	xar	ninc	atior	ns N	ove	mber	<sup>-</sup> 20	018		
			_				of El										
	-	′ks: 70					lect								ne: 3 H		
Answ	er a	Ill five units b	by cł	100S	ing		que *****		n fror	neo	ach	unit	(5 x 1	4 =	70 Ma	irks )	
							ļ	UNIT	-1								
1.	a)	Derive the re									actor	?					7M
	b)	Explain load	mod	deling	g and	l its c	hara			?							7M
2		Dofina tha fa		ina ta	rmo			OF	2								
<ul><li>2. Define the following terms</li><li>a) Maximum demand b) coincident factor c) Plant factor d) contribution factor</li></ul>								or									
		e) diversity f							)								4M
							ι	JNIT	-11								
3.	a)	What are the	•••						•			•			. C		7M
	b)	Draw the sir factors that i	•		•				•••	•	ary i	eeae	er and	me	ention tr		7M
							<b>,</b> -	OF		3							
4.		A 1- distrib and a load of to the volta (0.05+j0.1) determine th	f 80A ge  a /Km	at 0. It the If t	9pfl far he v	ag at end	its m . The	iidpo e im	int. B peda	oth t nce	he po per	ower Km	factors for go	s are &	return	ed is	
		(i) Voltage a			•	end											
		(ii) Phase an	ngle o	differ	ence	betv	veen	the	/olta	ges a	at bot	h the	e ends			1	4M
_			<i>.</i>			_		JNIT-						_			
5.	a) b)	How do you			•								•	?			7M 7M
	b)	Write the diff	lerer	ices	betw	een	naoc	or and OF		0001	Subs	statio	015?				7M
6.	a)	How do you	anal	yze a	a sub	ostati	on se	_		a wit	h 'n'	prima	ary fee	der	s?		7M
	b)	Write the be		•								•	•				7M
							U	INIT-	-IV								
7.	a)	Compare an correction?	nd ex	plain	the	role	of sł	nunt	and	serie	s ca	pacit	ors in	pov	ver facto		7M
	b)	Write short r	notes	on a	anv ti	wo m	etho	ds of	volta	ane o	contr	ol?					7M
	~)							OF		-ge							
8.		Explain the f	ollov	ving													
		a) Synchron	ous	capa	citors	5	· ·	ap c JNIT		ing a	and b	ooste	er trans	sfor	mers	1	4M
9.		Explain the general proc		-					prote	ective	e dev	/ices	and a	also	give th		4M
		- ·						OF	2								
10.		Write briefly			•	•	•										
		a) Fuse b) (	Circu	it rec	losu	res	c) lin **		ctiona	alize	r?					1	4M

Hall	Tick	et Number :	
Code		R-15	
Code	<b>.</b> 50	IV B.Tech. I Semester Regular Examinations November 2018 Digital Signal Processing ( Electrical and Electronics Engineering )	
		Time: 3 Hou ver all five units by choosing one question from each unit ( 5 x 14 = 70 Marks ) **********	Jrs
1.	a)	Obtain the DTFS coefficients of $x(n) = cos(\frac{16\pi}{13}n + \frac{\pi}{6})$ . Plot its magnitude and	
		phase.	6M
	b)	Find the N point DFT of the sequence.	
		$x(n) = 4 + \cos^2(\frac{2\pi n}{N})$ ; n = 0,1,2,N-1. For N=8	8M
		OR	
2.	a)	Evaluate linear convolution of the following sequences using DFT and IDFT $x(n) = \{2,1\}$ and $h(n) = \{1,2\}$	8M
	b)		
		<ul> <li>i) Convolution periodic discrete time sequences.</li> <li>ii) Time shift property of discrete time appriadic convence.</li> </ul>	6M
		ii) Time shift property of discrete time aperiodic sequence. UNIT-II	6M
3.	a)		
		$x(n) = \{\frac{1}{\sqrt{2}}, 1, \frac{1}{\sqrt{2}}, 0, -\frac{1}{\sqrt{2}}, -1, -\frac{1}{\sqrt{2}}, 0\}$	7M
	b)	The DFT X(K) of sequence is given as X(K) = $\{0, 2\sqrt{2} (1-j), 0, 0, 0, 0, 0, 2\sqrt{2} (1+j)\}$	
		Determine the corresponding time sequence x(n) using DIF-FFT and draw its flow graph.	7M
		OR	
4.	a)	What are the differences and similarities between DIT and DIF – FFT algorithm? Discuss in-place computation in the case of decimation in frequency algorithm.	6M
	b)	Let x(n) = $\left(1, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right)$ and h(n) = (1, 1, 1, 1). Compute the DFTs of x(n) and	
		h(n)by the decimation in frequency algorithm. Using the above results, evaluate the circular convolution of $x(n)$ and $h(n)$ .	8M
		UNIT–III	
5.	a)	Design an analog Butterworth filter that has a gain of -2dB at 20rad/sec. and attenuation in excess of 10dB beyond 30 rad/sec.	7M
	b)	Find H(z) using impulse invariance method for the following transfer function.	
		$(\mathbf{s} + \mathbf{a})$	

$$H_{a}(s) = \frac{(s+a)}{(s+a)^{2} + b^{2}}$$
7M

OR

- 6. a) Design a Butterworth low pass digital filter using bilinear transformation to meet the following specification.
  - i) An acceptable pass band ripple of 1db
  - ii) A pass band edge of 0.3 rad. &
  - iii) Stop band attenuation of 40db or greater beyond 0.6 rad. 8M
  - b) The transfer function of a system is given by

$$H(z) = \frac{\frac{1}{4}z^{-1}}{1 - \frac{3}{4}z^{-1} + \frac{1}{8}z^{-2}}$$

Realize the above using direct form I, direct form II.

- 7. a) Explain the frequency sampling method of designing FIR filters and draw the corresponding block diagram.
  - b) The frequency response of an FIR filter is given by

$$H() = e-j3 (1 + 1.8\cos 3 + 1.2\cos 2 + 0.5\cos )$$

Determine the coefficients of the impulse response h(n) of the FIR filter 7M

OR

8. a) Design a FIR low pass filter with the frequency response, using rectangular window.

$$h_d(\omega) = e^{\frac{-j\omega_d(N-1)}{2}} - \frac{\pi}{2} \le \omega \le \frac{\pi}{2}$$
$$= 0 \qquad ; \text{ elsewhere}$$

For N=7

b) A filter is to be designed with the following desired frequency response

$$H_d(\omega) = 0; -\frac{n}{4} < \omega < \frac{n}{4}$$
$$= e^{-j2\omega}; \qquad \frac{n}{4} < |\omega| < n$$

Find the frequency response of the FIR filter designed using rectangular window defined as given below:  $w_R(n) = 1$ ; -5 n 5 7M

UNIT–V

- a) Analyse the basic concepts of spectral analysis of non-stationary signals.
   Explain how short-time Fourier transform used in the analysis.
   7M
  - b) With the diagram, explain the oversampling sigma-delta A/D converter structure.
     7M

OR

- 10. a) Why signal compression is required? With the relevant block diagram discuss<br/>the functioning of signal compression system.7M
  - b) Explain the concept of single echo filter and multiple echo filter of time domain operations in musical sound processing.
     7M

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7M

6M

7M

Hall	Tick	ket Number :	_
Code	: 5G	R-15	
		V B.Tech. I Semester Regular Examinations November 2018	
		Principles of Power Quality	
14-		(Electrical and Electronics Engineering)	
		arks: 70 all five units by choosing one question from each unit ( 5 x 14 = 70 Marks *******	
		UNIT–I	
1.	a)	Explain the power quality evaluation procedure with model diagram.	7M
	b)		
		and short-voltage variations.	7M
0		OR	714
2.	a) b)		7M 7M
	b)	Explain CBEMA and ITI curves with neat diagram.	7M
3.	a)		7M
	b)		7M
	,	OR	
4.	a)	Explain the devices used for overvoltage protection.	7M
	b)	Briefly explain influence of voltage sags with motor starting.	7M
		UNIT–III	
5.	a)	Explain the phenomena of Harmonics versus transients in detail.	7M
	b)	Explain different harmonic sources from Industrial loads.	7M
	、	OR	
6.	a)		7M
	b)		7M
7.	a)	<b>UNIT-IV</b> Explain principles of over voltage protection.	7M
	b)		7 101
	~)	equipment Explain them in brief.	7M
		OR	
8.	a)	Explain briefly about long duration and short duration voltage variations.	7M
	b)		
		voltage regulation.	7M
0		UNIT-V Evaluin objectives of banch marking and evaluin banch marking process in datail	714
9.	a) b)	Explain objectives of bench marking and explain bench marking process in detail. Explain history of power quality monitoring standards.	7M 7M
	0)		7 171
10.	a)		7M
	b)		7M
		***	

	На	Il Ticket Number :	
	Cod	de: 5G271 R-15	
	M	IV B.Tech. I Semester Regular Examinations November 2018 <b>Power Semiconductor Drives</b> (Electrical and Electronics Engineering) ax. Marks: 70 Time: 3 Hou	rc
	7010	Answer all five units by choosing one question from each unit ( 5 x 14 = 70 Marks ) <b>UNIT-I</b>	15
1.	a)	Explain with neat block diagram about Electric Drive?	7M
	b)	Discuss the Advantages of Electrical Drive over Mechanical Drives?	7M
		OR	
2.	a)	Derive Expressions for armature Voltage & Speed-Torque relation of DC Separately Excited motor fed from a three phase fully controlled Rectifier?	7M
	b)	The speed of a separately excited dc motor is controlled by means of a 3 phase semi converter from a 3 phase 415V 50Hz supply. The motor constants are inductance 10 mH, resistance 0.9 ohm and armature constant 1.5 v-s/rad. calculate speed of the motor at a torque of 50 Nm when the converter is fired at 45 <sup>o</sup> . Neglect losses in the converter.	7M
		UNIT-II	7 1 1 1
3.	a)	Explain Braking methods for DC Separately Excited Motor?	5M
	b)	<ul> <li>A 220V, 1000rpm, 60A separately excited motor with armature resistance of 0.6Ω fed from a Circulating current dual converter with AC source voltage line voltage=165V. determine converter firing angles for the following operating points:</li> <li>i. Motoring operation at rated motor torque and 900rpm</li> </ul>	
		ii. Braking operation at rated motor torque at 900 rpm	
		iii. Motoring operation at rated motor torque and –900rpm	
		iv. Braking operation at rated motor torque at –900rpm	9M
4.	a)	<b>OR</b> A single phase, 230V, 50Hz supply-feeds a separately excited DC motor through two single phase semi converters, one for the end one for the armature. The firing angle for the semi converters fields is zero, the field resistance is $200\Omega$ and armature resistance $R_a$ =0.3 $\Omega$ . The load torque is 50 N-m at 900 r.p.m, the voltage constant is 0.8 V/A – rad / sec and the torque constants is 0.8 N-m/A <sup>2</sup> . Assume that armature and field currents are continuous and constant. And neglect the losses. Find the following	
		ii. Firing angle of converts in the armature circuit and	1014
	b)	iii. Power factor of convert in the armature circuit.	10M 4M
	0)	Comment on Regenerative Braking method of DC Series Motors?	4111
5.	a)	Draw and Explain First Quadrant and Second Quadrant operation of SEDCM when it is fed from a chopper?	5M
	b)	A 230V separately excited dc motor takes 50A at a speed of 800rpm. It has armature resistance of 0.4. This motor is controlled by a chopper with an input voltage of 230V and frequency of 500Hz. Assuming continuous conduction through-out, calculate and plot speed- torque characteristics for:	
		<ul> <li>Motoring operation at duty ratios of 0.3 and 0.6.</li> <li>Beggenerative broking operation at duty ratios of 0.7 and 0.4.</li> </ul>	014
		ii. Regenerative braking operation at duty ratios of 0.7 and 0.4.	9M

Code: 5G271

- 6. a) A 230V, 1000rpm, 30A separately excited motor has armature resistance and inductance of  $0.7\Omega$  and 50mH. Motor is controlled in regenerative braking by a chopper operating at 800Hz from a dc source of 230V assuming a continuous conduction.
  - i. Calculate duty ratio of chopper by rated torque and the speed of 800rpm
  - ii. What will be the motor speed for duty ratio of 0.6 and rated motor torque
  - iii. What will be the maximum allowable speed of motor. If a chopper has a maximum duty ratio of 0.9 and maximum allowable motor current is twice rated current.
  - iv. Calculate the power fed to source for operating condition in (iii).
  - b) Draw the Speed Torque relation and Characteristics of a chopper fed DC Series motor?
     4M

# UNIT-IV

- A Y-connected SCIM has the following ratings and parameters: 400V, 50 Hz, 4-pole, 1370 rpm, Rs= 2 , Rr'= 3 , Xs=Xr'= 3.5 Motor is controlled by a voltage source Inverter at constant v/f ratio. Inverter allows frequency variation from 10 to 50 Hz.
  - i) Calculate starting torque and current of this drive as a ratio of their values when motor is started at rated voltage and frequency?
  - ii) Speed for a frequency of 30Hz and 80% of full load torque with only variable method
  - b) List out differences between VSI and CSI fed drives?

### OR

A 3-phase, 415V, 50Hz, 4-pole, star connected induction motor has the following equivalent circuit parameters: R1 = 1.01 Ohms, R2'= 0.69 , X1=1.08 , X2=1.60 , Xm = 36 . The no load loss is negligible. The rated torque, proportional to square of the speed, is 42 N-m, at full load speed of 1450 rpm for a motor speed of 1290 rpm, determine (a) load torque, (b) rotor current (c) The stator supply voltage d) the motor input current I e) the motor input power Pi f) the slip for maximum current (g) the maximum rotor current I2'

## UNIT–V

- 9. a) Discuss about Speed control methods of Slip ring Induction Motor?
  - b) A Y-connected SRIM has the following ratings and parameters: 440V, 50 Hz, 6-pole Rs= 0.5 , Rr'= 0.4 , Xs=Xr'= 1.2 ,  $X_m = 50$  , stator to rotor turns ratio is 3.5 motor is controlled by a static rotor resistance control. External resistance is chosen such that the breakdown torque is produced at stand still for a duty ratio of zero. Calculate the value of the external resistance. How duty ratio should varied with speed so that the motor accelerates at maximum torque.

### OR

- 10. a) Briefly explain about the speed control methods for Squirrel Cage Induction motor? 4M
  - b) Derive the Detailed Expressions for Static Scherbius Drive?

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8M

6M

10M

14M

5M

9M

10M

(	Cod	e: 5G275	
	JUU	IV B.Tech. I Semester Regular Examinations November 2018	
		Renewable Energy Sources	
		(Electrical & Electronics Engineering)	
		. Marks: 70 Time: 3 Hours	
Α	nsw	rer all five units by choosing one question from each unit (5 x 14 = 70 Marks)	
		UNIT–I	
1.	a)	Compare the advantages and disadvantages between Conventional with Non-	
		conventional energy sources.	
	b)	Explain about the solar radiation and its measuring instruments.	
		OR	
2.	a)	Briefly describe the impact of solar power on environment.	
	b)	With neat sketches, explain briefly about different measuring instruments and their	
		applications.	
<b>`</b>		UNIT-II	
3.	a)	Briefly explain about the various types of Solar Collectors with their collector efficiency.	
	b)	With a neat sketch, explain the working of solar pond.	
4.	a)	<b>OR</b> Name the various types of Solar water heating systems and explain briefly about each	
т.	u)	of them.	
	b)	Compare different types of solar collectors.	
	-,	UNIT-III	
5.	a)	List out the various factors considered for the site selection of wind energy extraction	
	,	through wind turbine.	
	b)	Describe the various methods of ocean thermal electric power generation.	
		OR	
6.		Briefly explain the applications of Wind Energy and also derive the expression for	
		power for WECS.	1
-	- )		
7.	a)	What are the Advantages and Disadvantages of biogas generation?	
	b)	Describe the characteristics of the materials used for different components of a power plant using geothermal energy.	
		OR	
8.	a)	With a neat sketch, explain the working principle and operation of geothermal generation.	
	b)	Explain the difference between fixed dome type and floating drum type biogas plant.	
	-,		
9.	a)	Explain the need of Direct Energy Conversion.	
	b)	Compare Thermo-electric generators with MHD generators.	
	,	OR	